ADVT. for Tender Notice

Institute Website

CENTER FOR HEALTHCARE SCIENCE & TECHNOLOGY

Indian Institute of Engineering Science and Technology, Shibpur; Howrah-711103

Web Tender Advt. No: CHST/Web/D/4	Dated: 27.12.2017
	2 400 41 211212021

Sealed tenders are invited by the Centre for Healthcare Science & Technology, Indian Institute of Engineering Science and Technology, Shibpur, Howrah-711103 for the supply of laboratory items/works.

Tender Documents containing details of the items and terms and conditions may be downloaded from the university website and completed bidding documents are to be submitted to the Head, Centre for Healthcare Science & Technology, Indian Institute of Engineering Science and Technology, Shibpur; Howrah-711103 or dropped into the Tender Box kept in the Center within ten working days of publishing the tender.

Enclosed: Specification of the Items.

Prof. Amit Roy Chowdhury Head, Centre for Healthcare Science and Technology

Specification of the items:

Instrument	Specifications	
Op-Amp Trainer	□ Covers Op-Amp (741) & its various applications	
	□ Allows study of timer using 555 IC	
	\Box Study of F/V, V/F using LM331	
	□ On-board Resistor, Capacitor, Diode and Potentiometer bank of	
	different values. Bread board area allows construction of circuits using external	
	components along with on board resources.	
	□ On-board fixed power supply and variable regulated positive and	
	negative power supply.	
	$\Box \pm 15V, \pm 12$ and $\pm 5V$ fixed DC power supply	
	\Box DC 1.5 to 10V, -1.5 to -10V variable power supply	
	\Box IC /41 Op-Amp stage \Box 555 IC stage \Box LM331 IC stage. \Box 16 pin ZIF	
	Socket 🗆 Resistor bank	
	□ Capacitor bank □ Potentiometers □ Diodes □ Zener diodes	
7ICDEE Tuginon	INPN ITANSISTOR IN IN-CHARMENT MOSFET ILLED I Blead board	
Kit	• Integrated 2.4GHZ, IEEE 802.13.4-compliant transceiver	
Λιι	 Integrated Chip Antenna. 12 CDIOs(Constal Dum ass Input/sutputs) are susilable. 	
	13 GPIOs (General Purpose input/outputs) are available	
	• 3 GPIOS for Analog inputs: On board Temperature, LDR sensor and variable	
	• 10 CDIOs for Digital Inputs/Outputs: On board Buzzar 3 sliding switches 3	
	• 10 Of 10s for Digital inputs/Outputs. On board Duzzer, 5 shalling switches, 5 Output I FDs, Relay, Status and Power I FDs	
	• USB A_B interfacing facility with PC	
	 User friendly GUI for accessing the ZigBee Modules 	
	 Transmit Power: ±20dBmE LB P (max) 	
	• RE Date Range: 250 kbps	
	• No Date Range: 250 Rops	
	OS Support: YD/Vista/Windows 7	
	Os Support: AP/ vista/ windows-/ On Record Device bounds:	
	On Duaru r'eripherais; Ralay	
	• 5V SPDT Mechanical Relay	
	 NO & NC LED indicator 	
	 Screw Terminal Connector for connecting external devices 	
	Buzzer	
	• Operating Voltage: 3-6V DC	
	• Tone Type: Single	
	LDR	
	• Light luminance: 0-300 Lux	
	Temperature Sensor	
	• Operating Temperature range: 0°C -120°C	
	• Scale Factor: 10 mV/°C	
	Switch & LED	
	• Three SMD output LEDs.	
	• Two SMD Switch for RESET & FACTORY RESET of ZigBEE MODULE	
	Three Toggle Slider Switches for applying inputs	
Wi-Fi TRAINER	WI-FI Tran receiver module with 16Bit microcontroller Transceiver	

<u>KIT</u>	☐ Integrated 2.4GHz, IEEE 802.11-compliant RF transceiver		
	□ Data rate: 1 to 11 Mbps for 802.11b / 6 to 54 Mbps for 802.11g, Integrated PCB		
	antenna		
	16 Bit Microcontroller: PIC24FJ256GB206		
	\square Integrated RTC 32 768 KHz quartz onboard		
	$\Box \text{Communication : up to } A \text{ LADT}_{2} \text{ SDL } 12C$		
	$\Box \text{Communication : up to 4 UAK1S, SP1, 12U}$		
	□ Flash : 16 Mbit & EEPROM : 64 Kbit		
	USB interface communication cable with PC		
	□ USB to RS232 Converter : FT232RL		
	\Box GPIO port with +5V DC and +3.3V DC		
	On Board peripherals		
	Relav		
	5V SPDT Mechanical Relay		
	\square NO & NC LED indicator		
	No & Ne LED indicator Sense: Terminal Diagle Compactor for external device		
	Screw Terminal Block Connector for external device		
	Buzzer		
	□ Operating Voltage : 3-6V DC		
	\Box Tone Type : Single		
	□ Osc. Frequency : 3.2KHz, 87Db		
	Temperature Sensor		
	\Box Operating Temperature range \cdot -55°C = TA = +150°C		
	\square Scale Factor : 10 mV/°C		
	Output Valtaga Panga : 100mV 2000mV		
	Service & LED		
	I hree user interface SMD LEDs & Switches		
Planar waveguide	Reflection/Refraction experiments are performed using quartz half cylindrical		
module	lens mounted on graduated rotational mounts.		
	□ Allows construction and characteristics study of single and multimode planer		
	waveguides.		
	□ Involves opto-electronics and optical components along with opto-mechanical		
	hardware.		
	Allows construction of planer waveguides using ion exchange method.		
	□ Extensive documentation to support development and study of waveguides.		
	□ Light coupling method using prism coupling technique		
	□ Allows study of fundamental preparties of geometrics entires		
	Anows study of fundamental properties of geometrica optics.		
	Wavelength 635nw.		
	Light - redvisible.		
	□ o/ppower 1mw.		
	□ complete system with power supply		
	Prism		
	□ Right angle prism (10X10X10mm. +0/-0.2mm)		
	□ Surface Quality :60/40		
	□ Surface flatnen 1 lambda		
	\square Refractive Index :>1 7		
	$\Box \text{Kunattive index .< 1.}$		
	□ Surface polished-diagonal, bone and back side.		
	\Box Surface unpolished-Two sided surface.		
	Colimetor		
	□ Gallilium construction		
	□ Magnification by 10X		

	Warneride	
	□ Singlemode, multimode waveguide	
	Substrate - Soda limeglass	
	□ Ion exchange using potatium ion(KnO3)bath	
Physics of Fiber	• He-Ne laser source with 1mW output power and 633.5nm wavelength	
Optic Lab	• Laser to fiber coupler with Lens adjustment facility to adjust beam into core of	
	fiber. Coupling Efficiency of $>70\%$ for SM fibers and $>90\%$ for MM fibers.	
	Wavelength of operation 180 to 2000nm power handling capacity more	
	than 1 watt	
	 Leser newer meter with senerate Sensor unit with stand and senerate display. 	
	• Laser power measurement of $2\mu W = 20W$ with $1 \mu W$ resolution. Dower density	
	unit, power measurement of $2\mu W \sim 20W$ with Thw resolution, Fower density	
	of 15KW/cm2, Sensor diameter of 20mm, Wavelength of operation $400 \sim 1100$	
	nm and calibrated to 633nm	
	• Optical fiber patch chords and accessories required for experimentation	
	purpose:	
	a. 9 micron single mode glass fiber patch chord	
	b. 62.5 micron multi mode glass fiber patch chord	
	c. 100 micron multi mode glass fiber patch chord	
	d. 9 micron single mode glass fiber pigtail	
	e. 100 meter 9 micron single mode glass fiber cable with ST connectors	
	f. 1000 meter 9 micron single mode glass fiber cable with ST connectors	
	g. ST to ST Matting Sleeve –2	
	h. Optical platform	
	i. Laser to fiber coupler holder	
	j. Laser Source holder	
	k. Fiber Holder with vertical and horizontal positioning facility	
	1 Display screen	

Fiber Ontic Laser	□ Type · Laser		
Source And	Central wavelength: 1310nm		
Detector Module	\square Spectral width : 1 nm		
2000001 11200001	\Box Output power : 1.5mW		
	\square Threshold Current : 15mA M	aximum	
	Detector		
		: PIN photo diode	
	□ Spectral bandwidth	: 1250nm ~ 1600nm	
	□ Responsivity	: 0.8A/W	
	□ Bandwidth	: 155MHz	
	□ Return loss	: 40dB	
	□ Reverse voltage,VR	: Maximum 30V	
	□ Reverse current, IR	: Maximum 500 μA	
	□ Maximum supporteed data rat	e: 3mbps	
	Pulse generator		
	□ Pulse width : Selectable from 30ns and 100ns		
	□ Pulse amplitude: 4Vpeak		
	EXPERIMENTS		
	□ I-V characteristics of Laser		
	□ P-I characteristics of Laser		
	Digital data transmission		
	□ Analog signal transmission		
	\Box PC to PC communication		
	\Box Used with FOM-2 to study	passive components	
	- Isolator		
	- Attenuator		
	- Coupler		
Chromatic	\Box Length of fiber	: 25 Kilometer	
Dispersion Module	□ Type of fiber	: Singlemode	
	□ Attenuation	: <=0.05dB/km@1285 ~1330nm and 1525nm ~1575nm	
	\Box Cable cut off wave length	: <= 1260nm	
	□ Chromatic dispersion	: <=3.5ps/(nm.km) @ 1285 nm ~ 1330nm)	
	□ Zero dispersion wavelength	: 1300nm ~1320nm	
	<wavelength<< th=""><th></th></wavelength<<>		
	td="">		
	□ Multimedia based interactive of	e-manual	
Vertically	Mechanical Structure: Vertic	ally articulated: open frame	
Articulated 5	• Degrees of Freedom : 5 rotat	ional axes and gripper	
AXIS Robot ARM	• Payload Capacity : 2.1 kg	Serre and Serre	
	• Reach : 610 m	m (24") with gripper	
	• Speed · 700 m	m/sec (27.6"/sec)	
	Repeatability :+ 0.18	mm(0.007")	
	Desition Feedback · Incren	nental ontical encoders	
	Homing · Mieron	switch on each axis	
	Actuators 12 V c	swhen on each axis	
	Actuators . 12 V C	ryo motor 2 finger parallel	
	Gripper DC set	5 mm (2.6"/2")	
	 Gripper Jaw Opening: 0-65/7 	$J \min(2.0 / 5)$	

• Transmission : Gears, timing belts, lead
Axis Range
\Box Axis 1 : Base rotation 310
\Box Axis 2 : Shoulder rotation +130/-35
\Box Axis 3 : Elbow rotation +130
\Box Axis 4 : Wrist pitch +130
\Box Axis 5 : Wrist roll ±570
CONTROLLER
□ Communication : USB type A cable connection to PC; Plug and play without
rebooting
□ Inputs/Outputs : 8 digital inputs; 4 analog inputs; 8 digital outputs (4 relay, 4 open collector): 2 analog outputs
☐ Microcontroller · Full featured NEC V853 RISC 32- bit microcontroller
Axis Servo Control : Real-time: PID: PWM Servo Axes : 8 (robot arm gripper
and 2 peripheral devices)
\Box User Memory Unlimited programs program lines and variables positions
Position Definition : Absolute. Relative. Cartesian. Joints. Encoders
□ Trajectory Control : Joint, Linear, Circular
□ Speed Definition : 100 speed settings (percentages): travel time definition:
millimeter per second (mm/sec) for robot linear movement Control Parameters :
160 user-accessible parameters
□ Safety Features : Emergency switch; short-circuit Protection; automatic shut-
down upon detection of impact, overheating, PC failure or communication error
SOFTWARE
SCORBASE: Robotic programming & operation software
RoboCell: 3D graphic simulation software (optional) enables offline design and
simulation of virtual robotic cell and online graphic tracking of actual cell
Accessories (optional): Teach pendant, linear belt conveyor, rotary index table,
linear slide bases, and sensors XY positioning table, parts feeders, I/O experiment
table, pneumatic grippers, End effectors, machine vision system, workbenches,
coordinate grid.